



Review Questions

Section 6.1

- **6.1** What are the two bursts that CPU schedulers are designed around?
- **6.2** True or False? Under preemptive scheduling, when a process switches from the running to the ready state, it may lose control of the CPU.

Section 6.2

6.3 List at least three different criteria for designing a CPU scheduling algorithm.

Section 6.3

- **6.4** What scheduling algorithm assigns the CPU to the process with the highest priority?
- **6.5** True or False? The multilevel feedback queue scheduling algorithm allows processes to migrate between different queues.
- **6.6** What scheduling algorithm assigns the CPU to the process that first requested it?
- **6.7** What scheduling algorithm assigns the CPU to a process for only its time slice (or time quantum?)
- **6.8** What scheduling algorithm assigns the CPU to the process with the shortest burst?

Section 6.4

- **6.9** What are the two types of contention scope for thread scheduling?
- **6.10** What are the two general hardware instructions that can be performed atomically?

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Section 6.5

- **6.11** What is more common on current systems, asymmetric or symmetric multiprocessing?
- **6.12** What are the two forms of processor affinity?
- **6.13** What are the two general approaches for load balancing?
- **6.14** What are the two ways to multithread a processing core?

Section 6.6

- **6.15** What are the two general types of real-time scheduling?
- **6.16** What real-time scheduling algorithm uses deadline as its scheduling criteria?
- **6.17** What real-time scheduling algorithm is used for scheduling periodic tasks with static priorities?

Section 6.7

- **6.18** What is the name of the default scheduling algorithm for current Linux systems?
- **6.19** True or False? A Windows thread is assigned both a priority class and a relative priority within that class.
- **6.20** If a thread on a Solaris system exhausts its time quantum, will it later be assigned a higher or lower priority?

Section 6.8

6.21 True or False? Deterministic modeling and simulations are similar strategies for evaluating scheduling algorithms.